

INVESTICE DO ROZVOJE VZDĚLÁVÁNÍ

# Agent-based Modeling and Simulation

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Tato prezentace je spolufinancována Evropským sociálním fondem a státním rozpočtem České republiky.



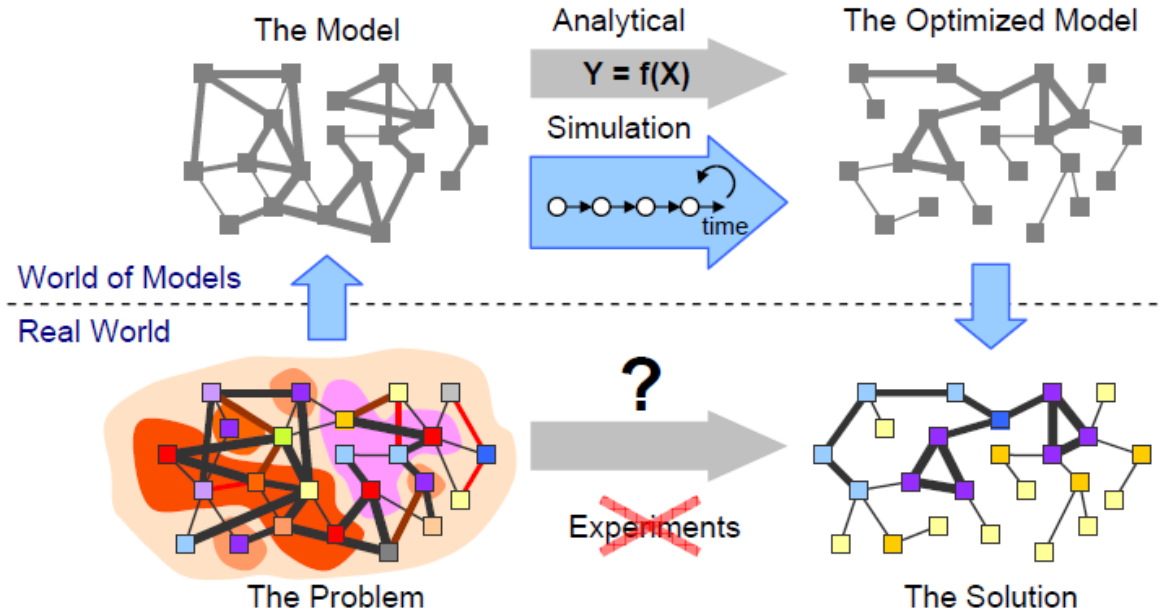
# Introduction





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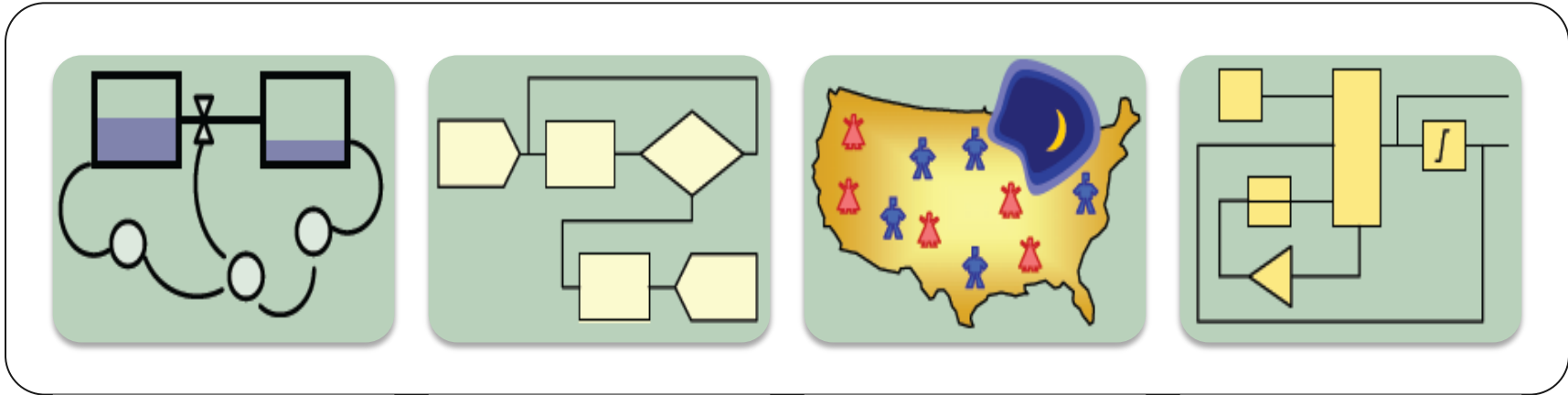
Simulation is a key tool for obtaining **insight** and **foresight** regarding the operation of complicated systems



From: Borshchev, A. et al (2004): From system dynamics and discrete event to practical agent based modeling: Reasons, techniques, tools



# S&M Approaches



## System dynamic

- states, feedbacks and delay structures
- continuous
- global, aggregate view

## Discrete Event

- entities and resources
- discrete, event-based
- global entity processing algorithm

## Agent Based

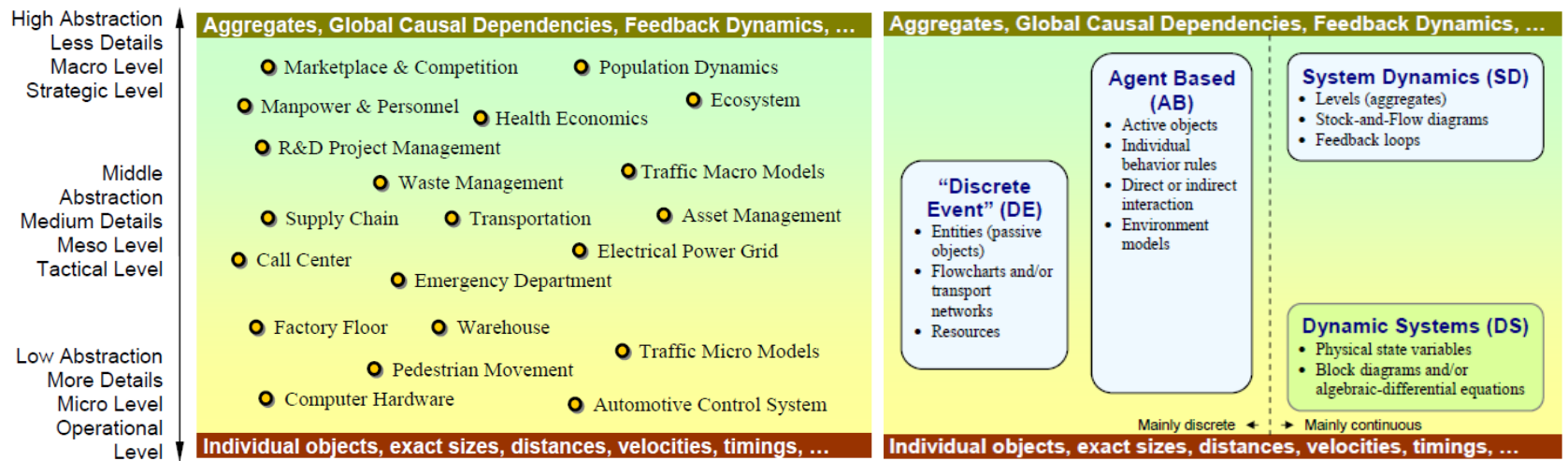
- active entities and the environment
- decentralized, individual perspective
- **global behavior emerges**

## Dynamic Systems

- state variables and differential equations
- direct physical meaning, no aggregation



# Levels of Abstraction



From: Borshchev, A. et al (2004): From system dynamics and discrete event to practical agent based modeling: Reasons, techniques, tools





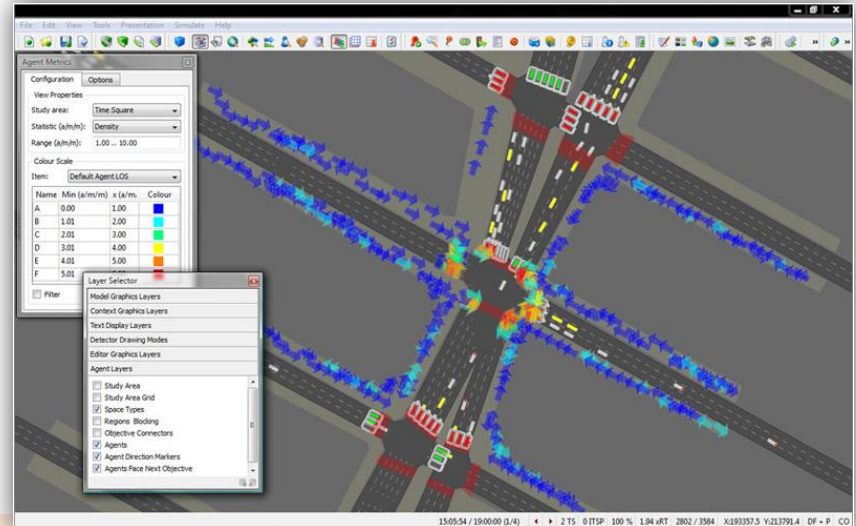
# Illustrative Example

## Pedestrian simulation

- Each pedestrian modeled as an agent sensing the environment and interacting with other pedestrian agents

## The model allows to

- determine crowd flows and densities under various scenarios
- optimize crowded public spaces for capacity, comfort and safety



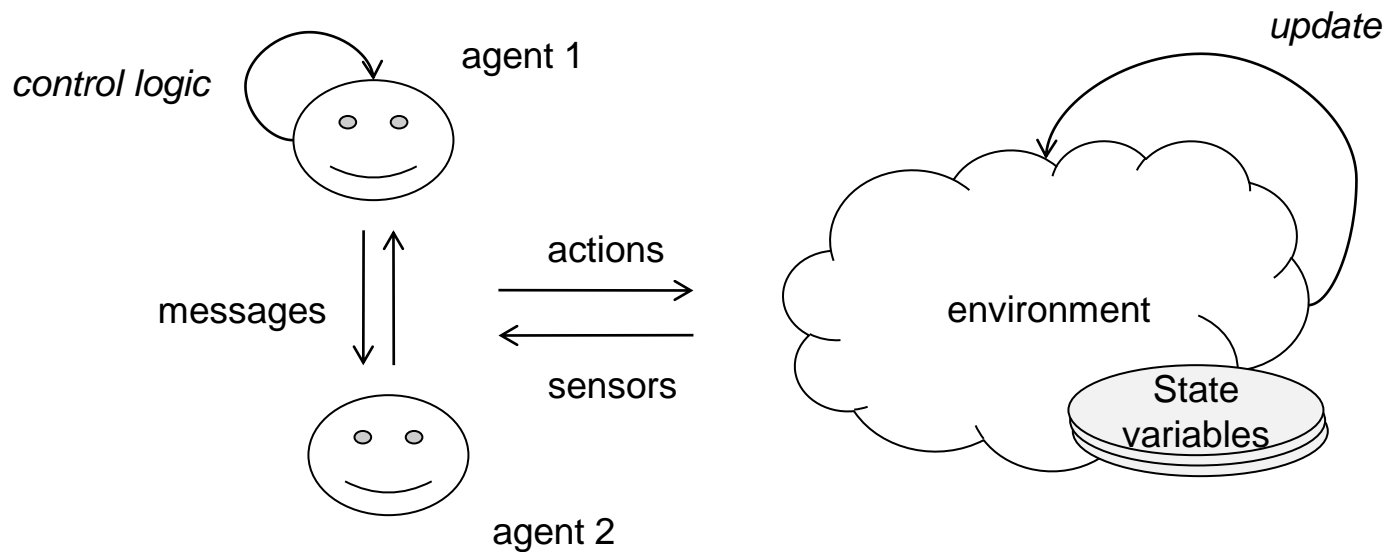


# Architecture of the Agent-based Simulation





# Structure of the Agent-based Simulation



Agents drive the model through local behaviors and direct and indirect interaction with each other and with the environment

Environment state is modified by agent actions and/or agent-independent processes (e.g. weather)





# Agent

Key component of an-agent based model

Proactive entity acting towards its objective

Key operations

- processing sensory inputs
- selecting actions to perform
- managing communication

Additional operations

- adaptation
- deliberation



# Agent's Control Logic

BDI (belief-desire-intention) architecture as a foundation

Simple control logic implementations used in practice

- (hierarchical) finite state machines
- rule engines
- scripts

Calls to special-purpose subsystems

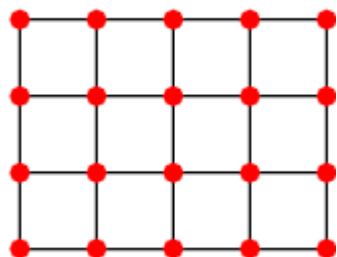
- navigation
- environment perception



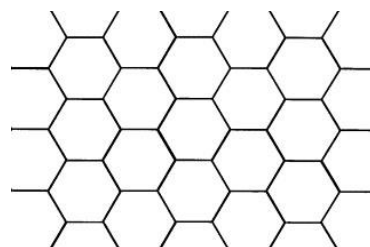
# Environment

Shapes agent's operation, mediates inter-agent interaction, can impact inter-agent communication

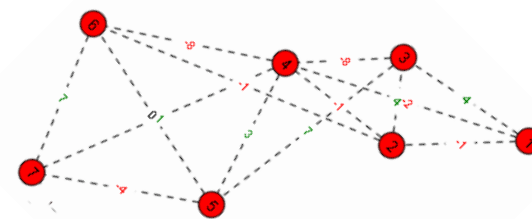
## Abstract environments



rectangular grid



hexagonal grid



general graph

Realistic/VR: open landscape, urban, indoor



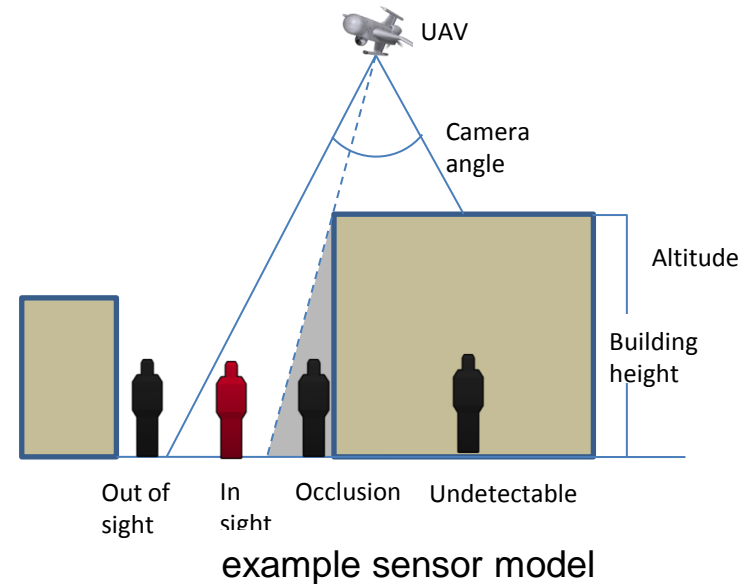
# Sensors

Enables the agent to access the environmental state

- low-level – direct perception (e.g. image from a camera)
- high-level – interpreted scene (e.g. walls, people)

Efficient implementation crucial in more complex environments

- partitioning
- caching





# Developing agent-based simulations

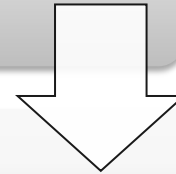




# Development Cycle

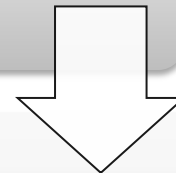
## Design

- identify agents and environmental features
- choose the right modeling abstraction critical



## Implementation

- agent's control logic
- environmental features and dynamics



## Calibration and Validation

- micro-level and macro-level
- real-world data-based (if possible)



# Calibration and Validation

## Micro-level

- parameter correspondence (e.g. size, speed, visual range, ...)
- behavior correspondence (reaction under different circumstances)

## Macro-level

- compare outcome distributions
- comparison with real system traces (start from the same initial conditions)

Generally very difficult due to inherent complexity of the system



# Platforms and Tools

General platforms still only in an early stage

- academic: RePast, NetLogo
- commercial: AnyLogic
- A-Globe Simulation

Special-purpose platforms more mature

- traffic modeling: [AIMSUN](#)
- pedestrian modeling: [LEGION](#)

GIS tools and data sources

- Google Earth, NASA WorldWind
- <http://www.openstreetmap.org/>







# Advantages

## Captures **emergent phenomena**

- the whole is not a sum of parts – system cannot be abstracted
- non-linearity, discontinuity, phase-transitions

## Provides a natural description of the system

- agents easy to identify in the real-world system
- agents' activities easier to describe than global processes

## Flexible

- agents' behaviors can be easily extended/specialized
- size of the model can be scaled



# When to Use

Complex interaction between entities

- interaction topology not fixed
- feedback relationships, network effects

Heterogeneity of entities

- each agent has a different behavior

Behavior of individuals is complex

- learning, adaptation

Unknown global process structure and/or parameters

Environment is crucial and agents are mobile



# Application Areas

## traffic and transport

- optimization of traffic networks, understanding and eliminating congestion

## pedestrians and crowds

- capacity optimization, evacuation procedures

## organizations

- organization design optimization, operation risk estimation

## markets and economies

## computer networks

- bandwidth usage estimation, worm infection modeling

## security

- crime modeling, vulnerability estimation





# Conclusions





# Conclusions

Most recent addition to modeling and simulation toolbox

Bottom-up approach

Most suitable for complex systems composed of autonomous, interacting entities

Allows high-fidelity models at the expense of high-computational cost

Mature tools exist for specific domains (e.g. transport, crowds)

General purpose platforms and tools still under development

